Matrices and Vectors - Summary

1. Vectors

A vector is a one-dimensional array of numbers.

- Row vector: [1 2 3]
- Column vector: [1; 2; 3]

Vectors represent quantities with direction and magnitude.

2. Matrices

A matrix is a two-dimensional array of numbers.

Example:

[1 2 3;

456]

This is a 2x3 matrix (2 rows, 3 columns).

3. Common Operations

- Addition/Subtraction: [1 2] + [3 4] = [4 6]
- Scalar Multiplication: 2 * [1 2] = [2 4]
- Matrix Multiplication: A(2x3) * B(3x1) = C(2x1)
- Transpose: [1 2 3]' = [1; 2; 3]
- Element-wise: [1 2] .* [3 4] = [3 8]
- Dot Product: [1 2] . [3 4] = 1*3 + 2*4 = 11
- Norm: ||v|| = sqrt(v1^2 + v2^2 + ... + vn^2)

4. Accessing Elements, Rows, Columns

- A(i,j): element at row i, column j
- A(i,:): entire row i
- A(:,j): entire column j

Example: A = [1 2 3; 4 5 6; 7 8 9]

 $A(2,3) = 6, A(1,:) = [1 \ 2 \ 3], A(:,2) = [2; 5; 8]$

5. Operations on Rows/Columns

Matrices and Vectors - Summary

- Multiply column 2 by 2: A(:,2) = A(:,2)*2
- Sum: sum(A,1) => sum by column, sum(A,2) => by row
- Replace: A(2,:) = [0 0 0]; A(:,3) = [1; 1; 1]

6. MATLAB Code Examples

A = [1 2 3; 4 5 6; 7 8 9];

val = A(2,3); % 6

row1 = A(1,:); % [1 2 3]

col3 = A(:,3); % [3; 6; 9]

A(:,2) = A(:,2) * 2;

A(1,:) = [10 11 12];

sum_row = sum(A, 2); % Sum of rows

mean_col = mean(A, 1); % Mean of columns

2D and 3D Plotting in MATLAB

1. 2D Plotting in MATLAB

2D plotting represents the relationship between two variables (x and y).

Basic Command: plot(x, y) Example: x = 0:0.1:2*pi; y = sin(x); plot(x, y); title('Sine Wave'); xlabel('x'); ylabel('sin(x)');

grid on;

Line Styles and Colors

plot(x, y, 'r--o') 'r' = red, '--' = dashed, 'o' = circle markers

Plotting Multiple Functions

plot(x, sin(x), 'b', x, cos(x), 'g'); legend('sin(x)', 'cos(x)');

Stem Plot (Discrete Data)

```
x = 1:5;
y = [3 5 2 6 4];
stem(x, y);
title('Stem Plot');
```

Bar Chart

bar([3 6 4 2]);

2D and 3D Plotting in MATLAB

Multiple Subplots in One Figure

subplot(2,1,1);

plot(x, sin(x));

title('Sine');

subplot(2,1,2);

plot(x, cos(x));

title('Cosine');

Filled Area: fill()

x = [1 2 3 4]; y = [2 3 1 5];

fill(x, y, 'g');

2. 3D Plotting Basics

plot3(x, y, z) plots lines in 3D space. Example: t = 0:0.1:10; x = sin(t); y = cos(t); z = t;plot3(x, y, z); xlabel('X'); ylabel('Y'); zlabel('Z'); grid on;

Surface and Mesh Plot

[X, Y] = meshgrid(-5:0.5:5); Z = sin(sqrt(X.^2 + Y.^2)); mesh(X, Y, Z); surf(X, Y, Z);

2D and 3D Plotting in MATLAB

Contour Lines (Level Curves)

contour(X, Y, Z);

General Tips

hold on - plot multiple items axis equal - equal axis scale grid on - show grid legend - describe plots

1. Solving Linear Equations (Ax = b)

Example:

A = [2 3; 4 1]; b = [8; 10]; x = A\b; % Output: x = [1; 2]

2. Solving a Single Symbolic Equation

syms x eq = $x^2 - 5^*x + 6 == 0$; sol = solve(eq, x); % sol = 2, 3

3. Solving Multiple Symbolic Equations

syms x y
eq1 = x + y == 5;
eq2 = x - y == 1;
sol = solve([eq1, eq2], [x, y]);
sol.x, sol.y

4. Solving Nonlinear Equations Numerically (fzero)

f = @(x) x^3 - x - 1;
root = fzero(f, 1);
root is approximately 1.3247

5. Solving Systems Numerically (fsolve)

 $f = @(v)[v(1)^2 + v(2)^2 - 4; v(1)^*v(2) - 1];$ x0 = [1, 1]; sol = fsolve(f, x0);

Solving Equations in MATLAB

6. Solving Polynomial Equations with roots()

coeff = [1 2 -3 1];

r = roots(coeff);

% r = [1; -3; -1] (example)

Tips

- Use double() to convert symbolic to numeric.
- Use pretty() or disp() for display.
- Use assume(x, 'real') to simplify.

Relational and Logical Operators in MATLAB

1. Relational Operators

Relational operators are used to compare values or arrays. They return logical results (1 for true, 0 for false).

Operator	Description	Example	Result
==	Equal to	5 == 5	1 (true)
~=	Not equal to	3 ~= 2	1 (true)
>	Greater than	7 > 2	1 (true)
<	Less than	3 < 4	1 (true)
>=	Greater than or equal to	6 >= 6	1 (true)
<=	Less than or equal to	2 <= 3	1 (true)

Example with arrays:

A = [1 2 3]; B = [3 2 1]; R = A > B % Output: [0 0 1]

2. Logical Operators

Logical operators are used with logical values (true/false or 1/0).

Operator	Description	Exan	nple	I	Result
&	Logical AND	true &	false	fa	lse
`	`	Logical	OR	`tr	ue
~	Logical NOT	~true		fa	lse
xor	Exclusive OR	xor(1,	0)	1	(true)

Example with arrays:

```
A = [true false true];
B = [false false true];
R = A & B
% Output: [0 0 1]
```

3. Combining Relational and Logical Operations

You can combine both relational and logical operators for condition checks:

x = 10; y = 5; (x > 5) & (y < 10) % Output: 1 (true)

4. Short-Circuit Logical Operators

These are used only with **scalar** (single) values:

Operator Description

۵۵ Short-circuit AND

Example:

a = 4; b = 2; (a > 1) && (b < 5) % Output: true

Control Flow in MATLAB: if, for, while

1. if Statement

The if statement is used to execute code based on a logical condition.

Syntax:

```
if condition
    statements
elseif another_condition
    statements
else
    statements
end
```

Example:

```
x = 10;
if x > 0
    disp('Positive number');
elseif x == 0
    disp('Zero');
else
    disp('Negative number');
end
```

2. for Loop

The for loop is used to repeat a block of code a specific number of times.

Syntax:

```
for index = start:step:end_value
    statements
end
```

Example:

```
for i = 1:2:5
    disp(['Value is: ', num2str(i)]);
end
% Output:
% Value is: 1
% Value is: 3
% Value is: 5
```

3. while Loop

The while loop repeats a block of code as long as a condition remains true.

Syntax:

```
while condition
statements
end
```

Example:

```
x = 1;
while x <= 5
    disp(['x = ', num2str(x)]);
    x = x + 1;
end
```

4. Comparison Summary

Feature	if	for	while
Purpose	Conditional execution	Loop with known iterations	Loop while condition is true
Renearc	-	•	Until the condition becomes false
Use Case	Decisions	0	Unknown number of repetitions

Mathematical Concepts: Laplace, Limit, Integral, Derivative

1. Laplace Transform

The Laplace transform is a mathematical tool used to transform time-domain functions into the frequency domain.

It simplifies the solution of differential equations, especially in control systems and circuit analysis.

Example:

```
syms t s
f = exp(-2*t); % Function f(t)
F = laplace(f, t, s); % Laplace Transform
% Result: F(s) = 1 / (s + 2)
```

2. Limit

The limit is a concept used to describe the behavior of a function as its variable approaches a certain value.

It is essential in calculus, especially for defining derivatives and integrals.

Example:

```
syms x
f = (sin(x) / x); % Function f(x)
limit(f, x, 0) % Limit as x approaches 0
% Result: 1
```

3. Integral

Integration is the reverse process of differentiation and is used to calculate the area under curves, among other things.

It is a fundamental concept in calculus.

Example:

```
syms x
f = x^2; % Function f(x)
integral_value = int(f, x); % Compute the integral
% Result: (x^3) / 3 + C
```

4. Derivative

The derivative represents the rate of change of a function.

It measures how a function changes as its input changes. Derivatives are key to understanding the behavior of functions in physics, engineering, and other fields.

Example:

```
syms x
f = x^2 + 3^*x; % Function f(x)
derivative_value = diff(f, x); % Compute the derivative
% Result: 2x + 3
```