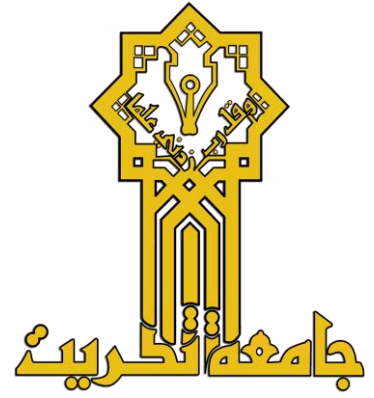




Transmission lines

Electrical Department-3rd Stage

Lecture Two

By

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□ INPUT IMPEDANCE OF TRANSMISSION LINE

- ❖ Consider a transmission line of length ℓ , characterized by γ and Z_0 , connected to a load Z_L as shown in Figure 1 (a).
- ❖ Looking into the line, the generator sees the line with the load as an input impedance Z_{in} . It is our intention in this section to determine the input impedance, the standing wave ratio (SWR), and the power flow on the line.
- ❖ Let the transmission line extend from $z = 0$ at the generator to $z = \ell$, at the load. First of all, we need the voltage and current waves in eqs. (1.1) and (1.2), that is,

$$V_s(z) = V_0^+ e^{-\gamma z} + V_0^- e^{\gamma z} \dots\dots\dots(1.1)$$

$$I_s(z) = \frac{V_0^+}{Z_0} e^{-\gamma z} - \frac{V_0^-}{Z_0} e^{\gamma z} \dots\dots\dots(1.2)$$

$$\text{Where } Z_0 = \frac{V_0^+}{I_0^+}$$

- ❖ To find V_0^+ and V_0^- , the terminal conditions must be given. For example, if we are given the conditions at the input, say

$$V_0 = V(z = 0), I_0 = I(z = 0) \dots\dots\dots(1.3)$$

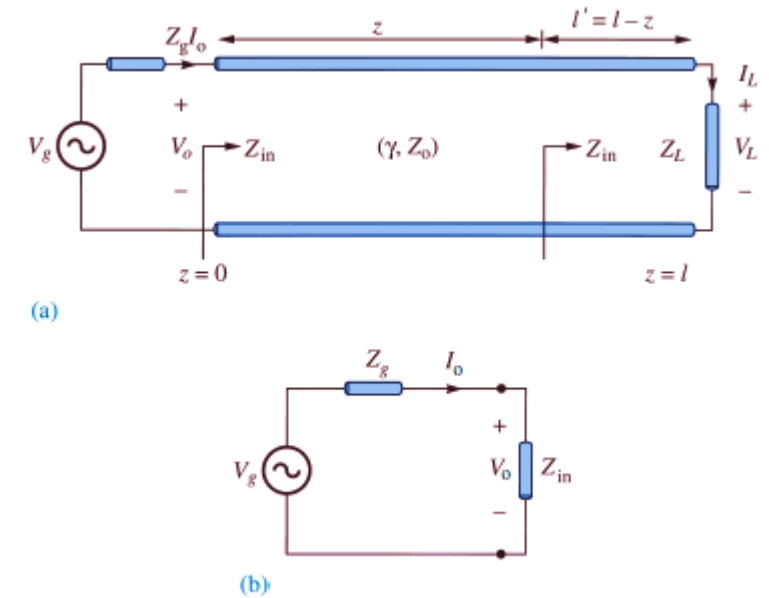


FIGURE 1 (a) Input impedance due to a line terminated by a load. (b) Equivalent circuit for finding V_0 and I_0 in terms of Z_{in} at the input.

substituting these into eqs. (1.1) and (1.2) results in

$$V_0^+ = \frac{1}{2} (V_0 + I_0 Z_0).....(1.4a)$$

$$V_0^- = \frac{1}{2} (V_0 - I_0 Z_0).....(1.4b)$$

If the input impedance at the input terminals is Z_{in} , the input voltage V_0 and the input Current I_0 are easily obtained from Figure 1(b) as

$$V_0 = \frac{Z_{in}}{Z_{in} + Z_g} V_g, \quad I_0 = \frac{V_g}{Z_{in} + Z_g} \dots\dots\dots (1.5)$$

On the other hand, if we are given the conditions at the load, say

$$V_L = V(z = l), I_L = I(z = l).....(1.6)$$

Substituting these into eqs. (1.1) and (1.2) gives

$$V_0^+ = \frac{1}{2} (V_L + I_L Z_0) e^{\gamma l}.....(1.7a)$$

$$V_0^- = \frac{1}{2} (V_L - I_L Z_0) e^{-\gamma l}(1.7b)$$

Next, we determine the input impedance $Z_{in} = \frac{V_S(z)}{I_S(z)}$ at any point on the line. At the generator, for example, eqs. (1.1) and (1.2) yield

$$Z_{in} = \frac{V_S(z)}{I_S(z)} = \frac{Z_0(V_0^+ + V_0^-)}{(V_0^+ - V_0^-)} \dots \dots \dots (1.8)$$

Substituting eq. (1.7) into (1.8) and utilizing the fact that

$$\frac{e^{\gamma l} + e^{-\gamma l}}{2} = \cosh \gamma l, \quad \frac{e^{\gamma l} - e^{-\gamma l}}{2} = \sinh \gamma l \dots \dots \dots (1.9a)$$

Or $\tanh \gamma l = \frac{\sinh \gamma l}{\cosh \gamma l} = \frac{e^{\gamma l} - e^{-\gamma l}}{e^{\gamma l} + e^{-\gamma l}} \dots \dots \dots (1.9b)$ We get

$$Z_{in} = Z_0 \left[\frac{Z_L + Z_0 \tanh \gamma l}{Z_0 + Z_L \tanh \gamma l} \right] \dots \dots \dots (1.10) \text{ --for (lossy transmission line)}$$

Although eq. (1.10) has been derived for the input impedance Z_{in} at the generation end, it is a general expression for finding Z_{in} at any point on the line.

To find Z_{in} at a distance l' from the load as in Figure 1(a), we replace l by l' .

A formula for calculating the hyperbolic tangent of a complex number, required in eq. (1.10), is found in Appendix I.

For a lossless line, $\gamma = j\beta$, $\tanh j\beta l = j \tan \beta l$, and $Z_0 = R_0$, so eq. (1.10) becomes

$$Z_{in} = Z_0 \left[\frac{Z_L + jZ_0 \tan \beta l}{Z_0 + jZ_L \tan \beta l} \right] \dots \dots \dots (1.11) \text{ For lossless transmission line}$$

showing that the input impedance varies periodically with distance l from the load. The quantity βl in eq. (1.11) is usually referred to as the electrical length of the line and can be expressed in degrees or radians.

□ Reflection coefficient (Γ)

We now define Γ_L as the voltage reflection coefficient (at the load). The reflection coefficient Γ_L is the ratio of the voltage reflection wave to the incident wave at the load; that is,

$$\Gamma_L = \frac{V_0^- e^{\gamma l}}{V_0^+ e^{-\gamma l}} \dots \dots \dots (1.12)$$

Substituting V_0^+ and V_0^- in eq. (1.7) into eq. (1.12) and incorporating $V_L = Z_L I_L$ gives

$$\Gamma_L = \frac{Z_L - Z_0}{Z_L + Z_0} \dots \dots (1.13)$$

The voltage reflection coefficient at any point on the line is the ratio of the reflected voltage wave to that of the incident wave.

That is,

$$\Gamma(Z) = \frac{V_0^- e^{\gamma Z}}{V_0^+ e^{-\gamma Z}} = \frac{V_0^-}{V_0^+} e^{2\gamma Z}$$

But $z = l - l'$. Substituting and combining with eq. (1.12), we get

$$\Gamma(Z) = \frac{V_0^-}{V_0^+} e^{2\gamma l} e^{-2\gamma l'} \dots \dots (1.14)$$

The current reflection coefficient at any point on the line is the negative of the voltage reflection coefficient at that point.

Thus, the current reflection coefficient at the load is $I_0^- e^{\gamma l} / I_0^+ e^{-\gamma l} = -\Gamma_L$

□ Standing Wave Ratio (SWR)

Standing wave ratio (SWR) is the ratio of the maximum magnitude or amplitude of a standing wave to its minimum magnitude. It indicates whether there is an impedance mismatch between the load and the internal impedance on a radio frequency (RF) transmission line, or waveguide.

we define the *standing wave ratio* as

$$s = \frac{V_{max}}{V_{min}} = \frac{I_{max}}{I_{min}} = \frac{1+|\Gamma_L|}{1-|\Gamma_L|} \dots \dots (1.15a)$$

$$|\Gamma_L| = \frac{s-1}{s+1} \dots \dots (1.15b)$$

It is easy to show that $I_{max} = V_{max}/Z_0$ and $I_{min} = V_{min}/Z_0$. The input impedance Z_{in} in eq. (1.11) has maxima and minima that occur, respectively, at the maxima and minima of the voltage standing wave. It can also be shown that

$$|Z_{in}|_{max} = \frac{V_{max}}{I_{min}} = sZ_0 \dots \dots (1.16a)$$

and

$$|Z_{in}|_{min} = \frac{V_{min}}{I_{max}} = \frac{Z_0}{s} \dots \dots (1.16b)$$

As a way of demonstrating these concepts, consider a lossless line with characteristic impedance of $Z_0=50 \Omega$. For the sake of simplicity, we assume that the line is terminated in a pure resistive load $Z_L =100 \Omega$ and the voltage at the load is 100 V (rms). The conditions on the line are displayed in Figure 2. Note from Figure 2 that conditions on the line repeat themselves every half-wavelength.

□ The average input power

The average input power at a distance l from the load is given by the below equation

$$P_{av} = \frac{1}{2} \text{Re} [V_s(l)I_s^*(l)]$$

where the factor $\frac{1}{2}$ is needed because we are dealing with the peak values instead of the rms values.

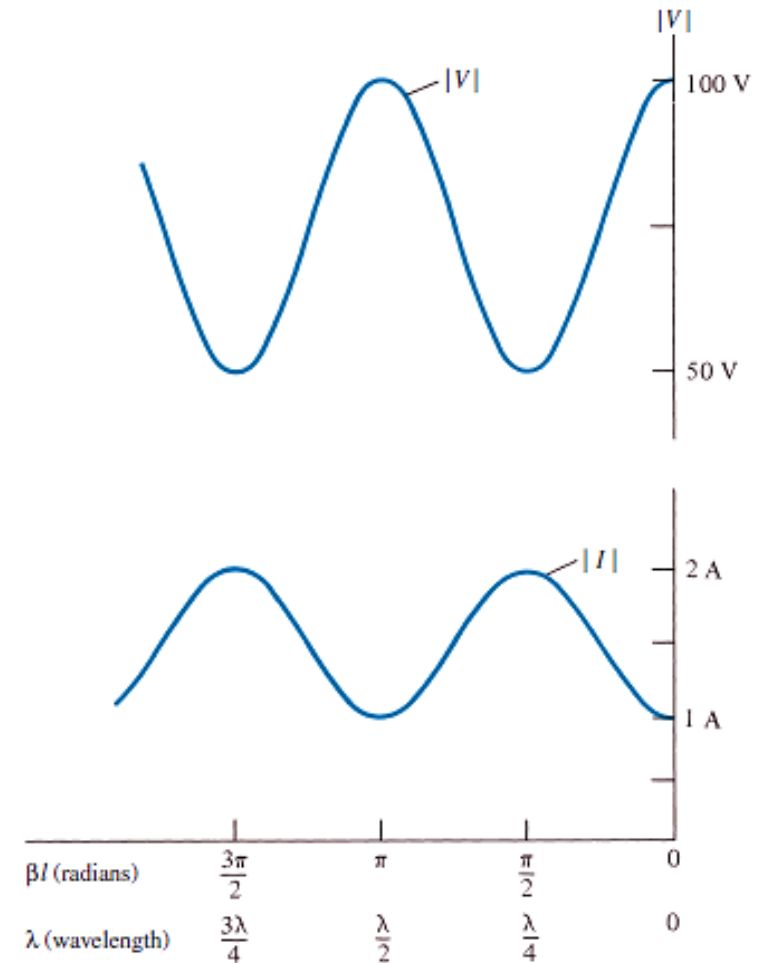


FIGURE 2 Voltage and current standing wave patterns on a lossless line terminated by a resistive load.

Assuming a lossless line we substitute eqs. (1.1) and (1.2) to obtain

$$P_{\text{ave}} = \frac{1}{2} \text{Re} \left[V_o^+ (e^{j\beta l} + \Gamma e^{-j\beta l}) \frac{V_o^{+\star}}{Z_o} (e^{-j\beta l} - \Gamma^\star e^{j\beta l}) \right]$$

$$= \frac{1}{2} \text{Re} \left[\frac{|V_o^+|^2}{Z_o} (1 - |\Gamma|^2 + \Gamma e^{-2j\beta l} - \Gamma^\star e^{2j\beta l}) \right]$$

Since the last two terms together become purely imaginary, we have

$$P_{\text{ave}} = \frac{|V_o^+|^2}{2Z_o} (1 - |\Gamma|^2) \quad \text{.....(1.18)}$$

The first term is the incident power P_i , while the second term is the reflected power P_r . Thus eq. (1.18) may be written as

$$P_t = P_i - P_r$$

where P_t is the input or transmitted power and the negative sign is due to the negative going wave (since we take the reference direction as that of the voltage/current traveling toward the right). We should notice from eq. (1.18) that the power is constant and does not depend on l , since it is a lossless line. Also, we should notice **that maximum power is delivered to the load when $\Gamma=0$, as expected.**

A. Shorted Line ($Z_L = 0$)

For this case this eq. $Z_{in} = Z_0 \left[\frac{Z_L + jZ_0 \tan \beta l}{Z_0 + jZ_L \tan \beta l} \right]$ will become

$$Z_{sc} = Z_{sc} |_{Z_L=0} = jZ_0 \tan \beta l \quad \text{..... (1.19)}$$

Also, from eqs. (1.13) and (1.15)

$$\Gamma_L = -1, \quad s = \infty$$

We notice from eq. (1.19) that Z_{in} is a pure reactance, which could be capacitive or inductive depending on the value of l . The variation of Z_{in} with l is shown in Figure 11.8(a).

B. Open-Circuited Line ($Z_L = \infty$)

In this case, this eq. $Z_{in} = Z_0 \left[\frac{Z_L + jZ_0 \tan \beta l}{Z_0 + jZ_L \tan \beta l} \right]$ becomes

$$Z_{oc} = \lim_{Z_L \rightarrow \infty} Z_{in} = \frac{Z_0}{j \tan \beta l} = -jZ_0 \cot \beta l \quad \text{....(1.20)}$$

Also, from eqs. (1.13) and (1.15)

$$\Gamma_L = 1, s = \infty$$

The variation of Z_{in} with l is shown in Figure 11.8(b). Notice from eqs. (1. 19) and (1.20) that

$$Z_{sc}Z_{oc} = Z_0^2 \dots \dots \dots (1.21)$$

C. Matched Line ($Z_L = Z_0$)

The most desired case from the practical point of view is the matched line i.e., $Z_L = Z_0$. For this case, this eq. $Z_{in} = Z_0 \left[\frac{Z_L + jZ_0 \tan \beta l}{Z_0 + jZ_L \tan \beta l} \right]$ reduces to

$$Z_{in} = Z_0 \dots \dots \dots (1.22)$$

Also, from eqs. (1.13) and (1.15)

$$\Gamma_L = 0, s = 1$$

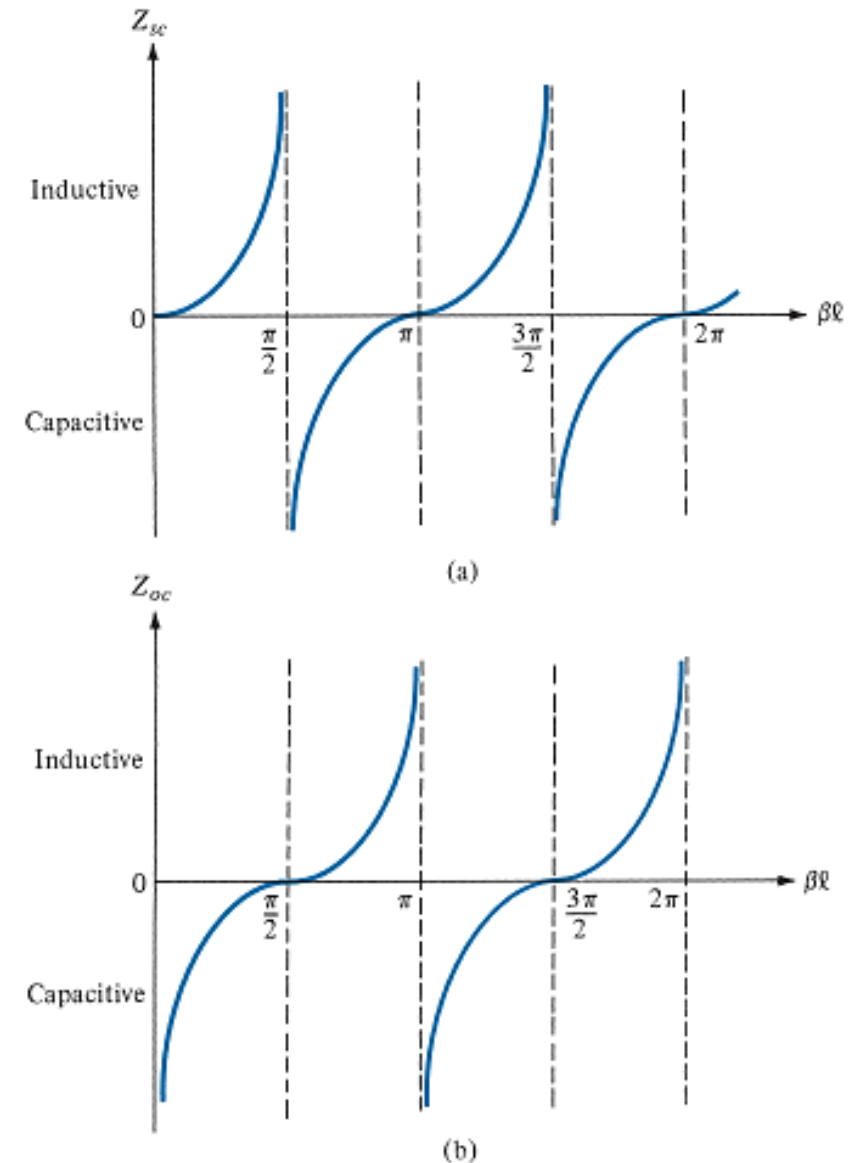


FIGURE 1.3 Input impedance of a lossless line: **(a)** when shorted, **(b)** when open.

that is, $V_0^- = 0$; the whole wave is transmitted, and there is no reflection. The incident power is fully absorbed by the load. Thus maximum power transfer is possible when a transmission line is matched to the load.

EXAMPLE 1

A certain transmission line 2 m long operating at $\omega = 10^6 \text{ rad/s}$ and $\alpha = 8 \frac{\text{dB}}{\text{m}}$, $\beta = 1 \frac{\text{rad}}{\text{m}}$ and $Z_0 = 60 + j40 \Omega$. If the line is connected to a source of $10 \angle 0^\circ \text{ V}$, $Z_g = 40 \Omega$ and terminated by a load of $20 + j50 \Omega$, determine

- (a) The input impedance
- (b) The sending-end current
- (c) The current at the middle of the line

Solution:

(a) Since $1 \text{ Np} = 8.686 \text{ dB}$,

$$\alpha = \frac{8}{8.686} = 0.921 \text{ Np/m}$$

$$\gamma = \alpha + j\beta = 0.921 + j1 \text{ /m}$$

$$\gamma \ell = 2(0.921 + j1) = 1.84 + j2$$

Using the formula for $\tanh(x + jy)$ in Appendix A.3, we obtain

$$\tanh \gamma \ell = 1.033 - j0.03929$$

$$\begin{aligned} Z_{\text{in}} &= Z_0 \left(\frac{Z_L + Z_0 \tanh \gamma \ell}{Z_0 + Z_L \tanh \gamma \ell} \right) \\ &= (60 + j40) \left[\frac{20 + j50 + (60 + j40)(1.033 - j0.03929)}{60 + j40 + (20 + j50)(1.033 - j0.03929)} \right] \end{aligned}$$

$$Z_{\text{in}} = 60.25 + j38.79 \Omega$$

(b) The sending-end current is $I(Z=0) = I_0$ From eq. (1.5),

$$I(z=0) = \frac{V_g}{Z_{in} + Z_g} = \frac{10}{60.25 + j38.79 + 40} \\ = 93.03 \angle -21.15^\circ \text{ mA}$$

(c) To find the current at any point, we need V_0^+ and V_0^- . But

$$I_0 = I(z=0) = 93.03 \angle -21.15^\circ \text{ mA}$$

$$V_0 = Z_{in} I_0 = (71.66 \angle 32.77^\circ)(0.09303 \angle -21.15^\circ) = 6.667 \angle 11.62^\circ \text{ V}$$

From eq. (1.4),

$$V_0^+ = \frac{1}{2}(V_0 + Z_0 I_0) \\ = \frac{1}{2}[6.667 \angle 11.62^\circ + (60 + j40)(0.09303 \angle -21.15^\circ)] = 6.687 \angle 12.08^\circ$$

$$V_0^- = \frac{1}{2}(V_0 - Z_0 I_0) = 0.0518 \angle 260^\circ$$

At the middle of the line, $z = \ell/2$, $\gamma z = 0.921 + j1$. Hence, the current at this point is

$$I_s(z = \ell/2) = \frac{V_0^+}{Z_0} e^{-\gamma z} - \frac{V_0^-}{Z_0} e^{\gamma z} \\ = \frac{(6.687 e^{j12.08^\circ}) e^{-0.921-j1}}{60 + j40} - \frac{(0.0518 e^{j260^\circ}) e^{0.921+j1}}{60 + j40}$$

Note that $j1$ is in radians and is equivalent to $j57.3^\circ$. Thus,

$$I_s(z = \ell/2) = \frac{6.687 e^{j12.08^\circ} e^{-0.921} e^{-j57.3^\circ}}{72.1 e^{j33.69^\circ}} - \frac{0.0518 e^{j260^\circ} e^{0.921} e^{j57.3^\circ}}{72.1 e^{j33.69^\circ}} \\ = 0.0369 e^{-j78.91^\circ} - 0.001805 e^{j283.61^\circ} \\ = 6.673 - j34.456 \text{ mA} \\ = 35.10 \angle 281^\circ \text{ mA}$$

THE SMITH CHART

The Smith chart is the most commonly used of the graphical techniques. It is basically a graphical indication of the impedance of a transmission line and of the corresponding reflection coefficient as one moves along the line

Used for calculations of transmission line characteristics such as Γ_L , s , and Z_{in} .

By assuming that the transmission line to which the Smith chart will be applied is **lossless** ($Z_0 = R_0$)

The Smith chart is constructed within a circle of unit radius ($|\Gamma_L| \leq 1$) as shown in Figure 1.4.

The construction of the chart is based on the relation in eq. (1. 13); that is

$$\Gamma_L = \frac{Z_L - Z_0}{Z_L + Z_0} \dots \dots (1.13)$$

or

$$\Gamma = |\Gamma| \angle \theta_\Gamma = \Gamma_r + j\Gamma_i \dots \dots \dots (1.23)$$

where Γ_r and Γ_i are the real and imaginary parts of the reflection coefficient Γ .

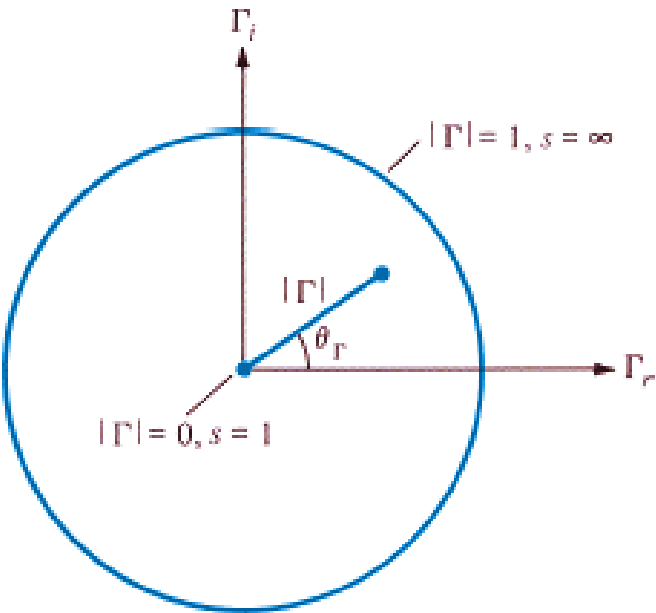


FIGURE 1.4 Unit circle on which the Smith chart is constructed.

Instead of having separate Smith charts for transmission lines with different characteristic impedances (e.g., $Z_0 = 60, 100, 120 \Omega$), we prefer to have just one that can be used for any line. We achieve this by using a normalized chart in which all impedances are normalized with respect to the characteristic impedance Z_0 of the particular line under consideration. For the load impedance Z_L , for example, the normalized impedance z_L is given by

$$z_L = \frac{Z_L}{Z_0} = r + jx \quad \dots(1.24)$$

Substituting eq. (1. 24) into eqs. (1. 13) and (1. 23) gives

$$\Gamma = \Gamma_r + j\Gamma_i = \frac{z_L - 1}{z_L + 1} \quad \dots(1.25)$$

or

$$z_L = r + jx = \frac{(1 + \Gamma_r) + j\Gamma_i}{(1 - \Gamma_r) - j\Gamma_i} \quad \dots(1.26)$$

Normalizing and equating real and imaginary components, we obtain

$$r = \frac{1 - \Gamma_r^2 - \Gamma_i^2}{(1 - \Gamma_r)^2 + \Gamma_i^2} \quad \dots(1.27)$$

$$x = \frac{2\Gamma_i}{(1 - \Gamma_r)^2 + \Gamma_i^2} \quad \dots(1.28)$$

Rearranging terms in eqs. (1. 27 & 28) leads to

$$\left[\Gamma_r - \frac{r}{1+r}\right]^2 + \Gamma_i^2 = \left[\frac{1}{1+r}\right]^2$$

....(1.29)

and

$$[\Gamma_r - 1]^2 + \left[\Gamma_i - \frac{1}{x}\right]^2 = \left[\frac{1}{x}\right]^2$$

....(1.30)

Each of eqs. (11.50) and (11.51) is similar to

$$(x - h)^2 + (y - k)^2 = a^2$$

which is the general equation of a circle of radius *a*, centered at (*h*, *k*). Thus eq. (11.50) is an *r*-circle (*resistance circle*) with

center at $(\Gamma_r, \Gamma_i) = \left(\frac{r}{1+r}, 0\right)$

radius = $\frac{1}{1+r}$

TABLE 1 Radii and Centers of *r*-Circles for Typical Values of *r*

Normalized Resistance (<i>r</i>)	Radius $\left(\frac{1}{1+r}\right)$	Center $\left(\frac{r}{1+r}, 0\right)$
0	1	(0, 0)
1/2	2/3	(1/3, 0)
1	1/2	(1/2, 0)
2	1/3	(2/3, 0)
5	1/6	(5/6, 0)
∞	0	(1, 0)

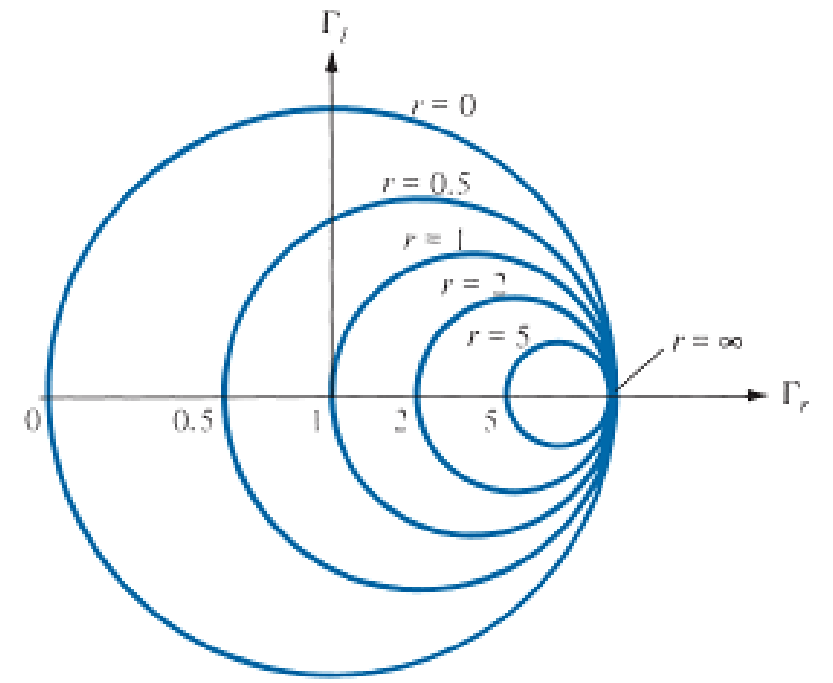


FIGURE 5 Typical r -circles for $r = 0, 0.5, 1, 2, 5, \infty$.

$$\sinh x = \frac{e^x - e^{-x}}{2}, \quad \cosh x = \frac{e^x + e^{-x}}{2}$$

$$\tanh x = \frac{\sinh x}{\cosh x}, \quad \coth x = \frac{1}{\tanh x}$$

$$\operatorname{csch} x = \frac{1}{\sinh x}, \quad \operatorname{sech} x = \frac{1}{\cosh x}$$

$$\sin jx = j \sinh x, \quad \cos jx = \cosh x$$

$$\sinh jx = j \sin x, \quad \cosh jx = \cos x$$

$$\sinh (x \pm y) = \sinh x \cosh y \pm \cosh x \sinh y$$

$$\cosh (x \pm y) = \cosh x \cosh y \pm \sinh x \sinh y$$

$$\sinh (x \pm jy) = \sinh x \cos y \pm j \cosh x \sin y$$

$$\cosh (x \pm jy) = \cosh x \cos y \pm j \sinh x \sin y$$

$$\tanh (x \pm jy) = \frac{\sinh 2x}{\cosh 2x + \cos 2y} \pm j \frac{\sin 2y}{\cosh 2x + \cos 2y}$$

$$\cosh^2 x - \sinh^2 x = 1$$

$$\operatorname{sech}^2 x + \tanh^2 x = 1$$

$$\sin (x \pm jy) = \sin x \cosh y \pm j \cos x \sinh y$$

$$\cos (x \pm jy) = \cos x \cosh y \mp j \sin x \sinh y$$