

Lecture -2-

Three-phase Rectification

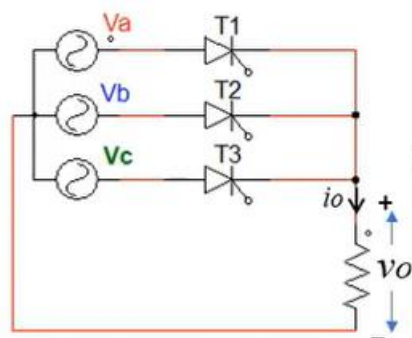
➤ Controlled Three -Phase Rectifiers

Features of Three -phase controlled rectifiers are:

- Operate from 3 phase ac supply voltage.
- The output can be controlled by substituting SCRs for diodes.
- They provide higher dc output voltage and higher dc output power.
- Higher output voltage ripple frequency.
- Filtering requirements are simplified for smoothing out load voltage and load current.
- Three-phase controlled rectifiers are extensively used in high-power variable speed industrial dc drives.

1) Half-Wave Rectifiers

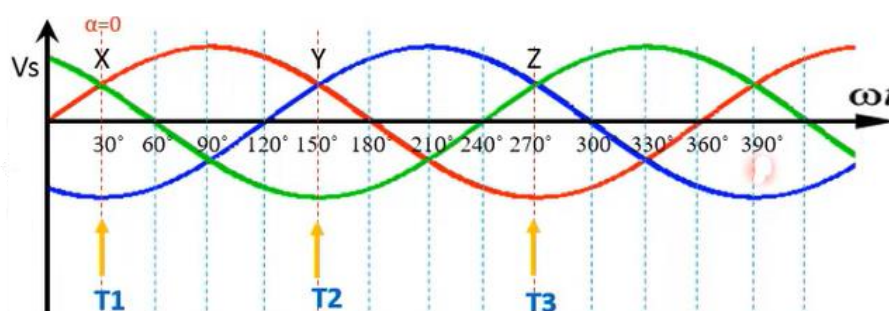
- Three single-phase half-wave converters are connected together to form a three-phase half-wave converter.
- The thyristor will conduct (ON state), when the anode-to-cathode voltage is positive and a firing current pulse is applied to the gate terminal. Delaying the firing pulse by an angle α controls the load voltage.
- The firing angle α is measured from the crossing point between the phase supply voltages.
- The possible range for gating delay is between $\alpha = 0^\circ$ and $\alpha = 180^\circ$, but because of commutation problems in actual situations, the maximum firing angle is limited to around 150° .

♦ Case of resistive load

$\omega t = 30^\circ \text{ to } 150^\circ$, T1 conduct

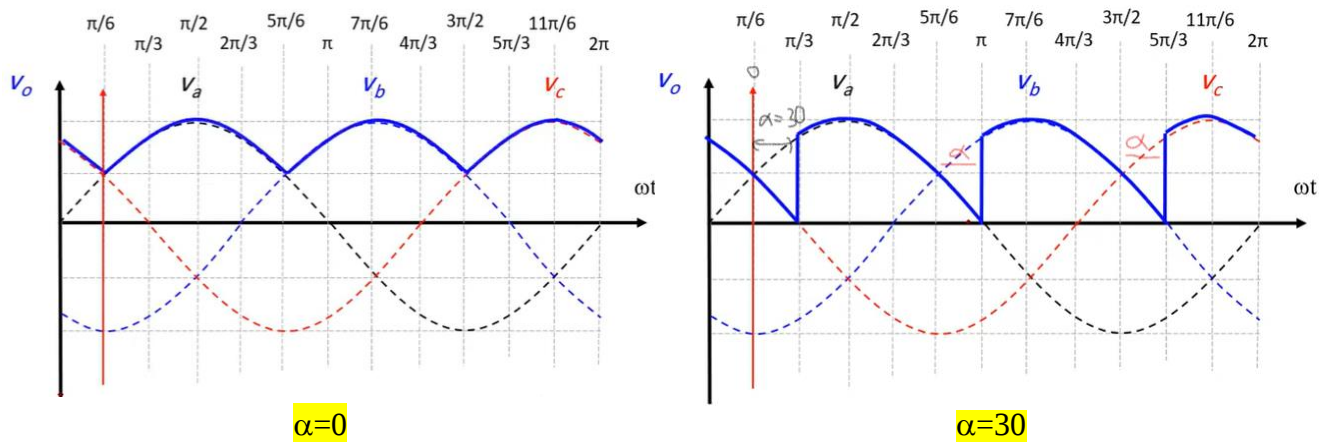
$\omega t = 150^\circ \text{ to } 270^\circ$, T2 conduct

$\omega t = 270^\circ \text{ to } 390^\circ$, T3 conduct



For Different Trigger Angles:

A. For $\alpha \leq 30^\circ$



$$V_{dc} = \frac{3}{2\pi} \left[\int_{\frac{\pi}{6} + \alpha}^{\frac{5\pi}{6} + \alpha} v_o \cdot d(\omega t) \right]$$

$$v_o = v_{an} = V_m \sin \omega t \text{ for } \omega t = (30^\circ + \alpha) \text{ to } (150^\circ + \alpha)$$

$$V_{dc} = \frac{3}{2\pi} \left[\int_{\frac{\pi}{6} + \alpha}^{\frac{5\pi}{6} + \alpha} V_m \sin \omega t \cdot d(\omega t) \right]$$

$$V_{dc} = \frac{3V_m}{2\pi} \left[\int_{\frac{\pi}{6} + \alpha}^{\frac{5\pi}{6} + \alpha} \sin \omega t \cdot d(\omega t) \right]$$

$$V_{dc} = \frac{3V_m}{2\pi} \left[(-\cos \omega t) \Big|_{\frac{\pi}{6} + \alpha}^{\frac{5\pi}{6} + \alpha} \right]$$

$$V_{dc} = \frac{3V_m}{2\pi} \left[-\cos \left(\frac{5\pi}{6} + \alpha \right) + \cos \left(\frac{\pi}{6} + \alpha \right) \right]$$

Note from the trigonometric relationship

$$\cos(A+B) = (\cos A \cos B - \sin A \sin B)$$

$$V_{dc} = \frac{3V_m}{2\pi} \left[-\cos\left(\frac{5\pi}{6}\right)\cos(\alpha) + \sin\left(\frac{5\pi}{6}\right)\sin(\alpha) + \cos\left(\frac{\pi}{6}\right)\cos(\alpha) - \sin\left(\frac{\pi}{6}\right)\sin(\alpha) \right]$$

$$V_{dc} = \frac{3V_m}{2\pi} \left[-\cos(150^\circ)\cos(\alpha) + \sin(150^\circ)\sin(\alpha) + \cos(30^\circ)\cos(\alpha) - \sin(30^\circ)\sin(\alpha) \right]$$

$$V_{dc} = \frac{3V_m}{2\pi} \left[-\cos(180^\circ - 30^\circ)\cos(\alpha) + \sin(180^\circ - 30^\circ)\sin(\alpha) + \cos(30^\circ)\cos(\alpha) - \sin(30^\circ)\sin(\alpha) \right]$$

$$\text{Note: } \cos(180^\circ - 30^\circ) = -\cos(30^\circ)$$

$$\sin(180^\circ - 30^\circ) = \sin(30^\circ)$$

Therefore

$$V_{dc} = \frac{3V_m}{2\pi} \left[+\cos(30^\circ)\cos(\alpha) + \sin(30^\circ)\sin(\alpha) + \cos(30^\circ)\cos(\alpha) - \sin(30^\circ)\sin(\alpha) \right]$$

$$V_{dc} = \frac{3V_m}{2\pi} \left[2\cos(30^\circ)\cos(\alpha) \right]$$

$$V_{dc} = \frac{3V_m}{2\pi} \left[2 \times \frac{\sqrt{3}}{2} \cos(\alpha) \right]$$

$$V_{dc} = \frac{3V_m}{2\pi} \left[\sqrt{3} \cos(\alpha) \right] = \frac{3\sqrt{3}V_m}{2\pi} \cos(\alpha)$$

Where

$$V_{Lm} = \sqrt{3}V_m = \text{Max. line to line supply voltage for a 3-phase star connected transformer.}$$

$$V_{dc} = \frac{3V_{Lm}}{2\pi} \cos(\alpha)$$

$$I_{dc} = \frac{V_{dc}}{R} = \frac{3\sqrt{3}V_m}{2\pi R} \cos \alpha$$

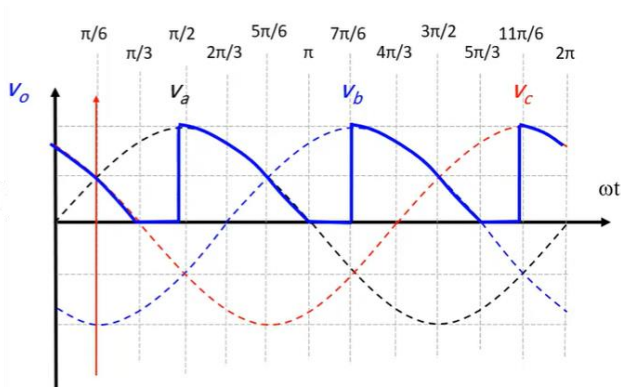
$$V_{rms} = \sqrt{\frac{3}{2\pi} \int_{\frac{\pi}{6}-\alpha}^{\frac{5\pi}{6}+\alpha} (V_m \sin \omega t)^2 d\omega t} = \sqrt{3}V_m \sqrt{\frac{1}{6} + \frac{\sqrt{3}}{8\pi} \cos 2\alpha}$$

$$I_{rms} = \frac{V_{rms}}{R} = \frac{\sqrt{3}V_m}{R} \sqrt{\frac{1}{6} + \frac{\sqrt{3}}{8\pi} \cos 2\alpha}$$

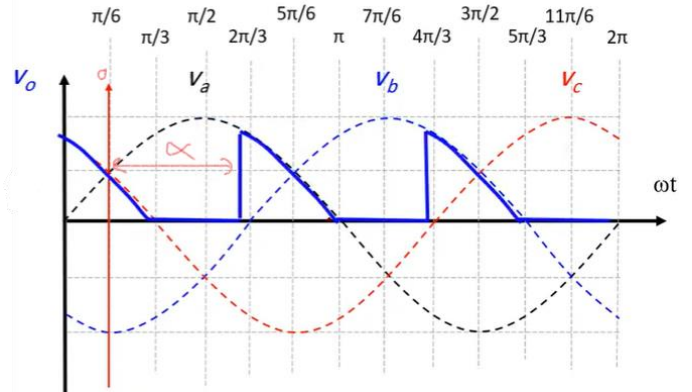
→ (at Load)

B. For $\alpha > 30^\circ$

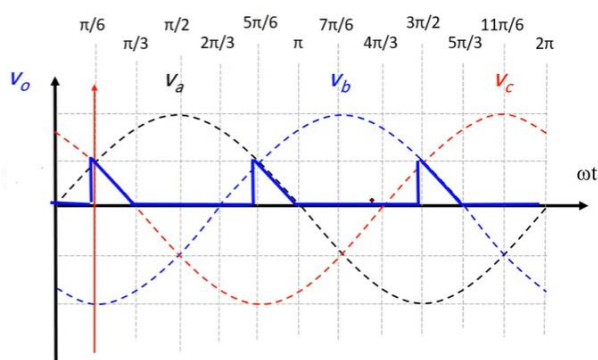
T_1 is triggered at $\omega t = (30^\circ + \alpha)$ and T_1 conducts up to $\omega t = 180^\circ = \pi$ radians. When the phase supply voltage v_{an} decreases to zero at $\omega t = \pi$, the load current falls to zero and the thyristor T_1 turns off. Thus T_1 conducts from $\omega t = (30^\circ + \alpha)$ to (180°) .



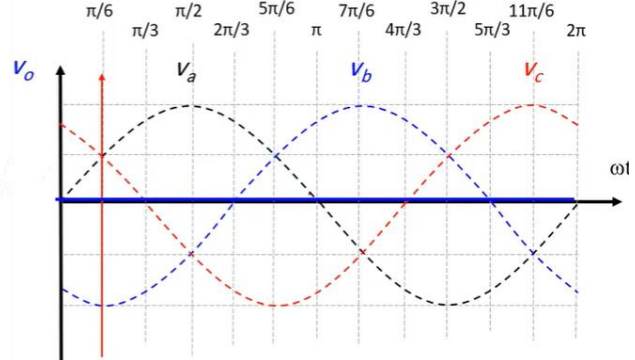
$\alpha = 60$



$\alpha = 90$



$\alpha = 120$



$\alpha = 150$

❑ For $\alpha > 30^\circ$ the load current is discontinuous for R load only, but in this case $\alpha > 150^\circ$ is not possible

$$V_{dc} = \frac{3}{2\pi} \int_{\frac{\pi}{6} + \alpha}^{\pi} V_m \sin \omega t \, d\omega t$$

$$V_{dc} = \frac{3}{2\pi} \left[\int_{\alpha + 30^\circ}^{180^\circ} V_m \sin \omega t \, d(\omega t) \right]$$

$$V_{dc} = \frac{3V_m}{2\pi} \left[-\cos \omega t \right]_{\alpha+30^\circ}^{180^\circ}$$

$$V_{dc} = \frac{3V_m}{2\pi} \left[-\cos 180^\circ + \cos(\alpha + 30^\circ) \right]$$

Since $\cos 180^\circ = -1$,

We get $V_{dc} = \frac{3V_m}{2\pi} \left[1 + \cos(\alpha + 30^\circ) \right]$

$$I_{dc} = \frac{V_{dc}}{R} = \frac{3V_m}{2\pi R} (1 + \cos(\frac{\pi}{6} + \alpha))$$

$$V_{rms} = V_m \sqrt{\frac{3}{4\pi} (\frac{5\pi}{6} - \alpha + \frac{1}{2} \sin(\frac{\pi}{3} + 2\alpha))}$$

$$I_{rms} = \frac{V_{rms}}{R} = \frac{V_m}{R} \sqrt{\frac{3}{4\pi} (\frac{5\pi}{6} - \alpha + \frac{1}{2} \sin(\frac{\pi}{3} + 2\alpha))}$$

→ (at Load)

$$I_{T,avg} = I_{s,avg} = \frac{I_{o,avg}}{3}$$

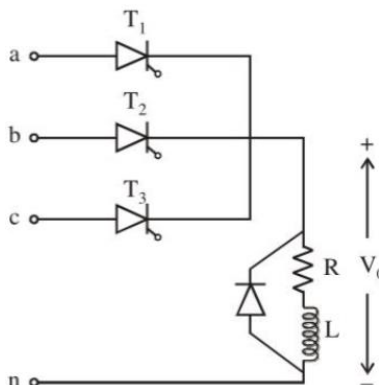
$$I_{s,rms} = I_{T,rms} = \frac{I_{o,rms}}{\sqrt{3}}$$

$$P_o = R \cdot I_{o,rms}^2$$

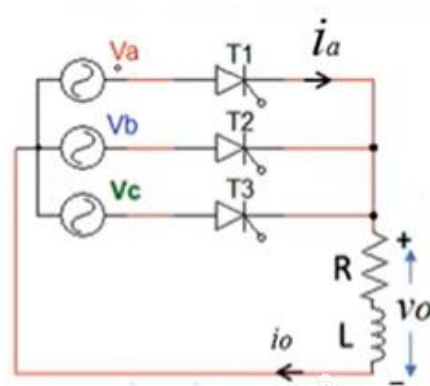
$$S = 3 V_{s,rms} \cdot I_{s,rms} \quad (\text{apparent power})$$

$$PF = \frac{P_o}{S}$$

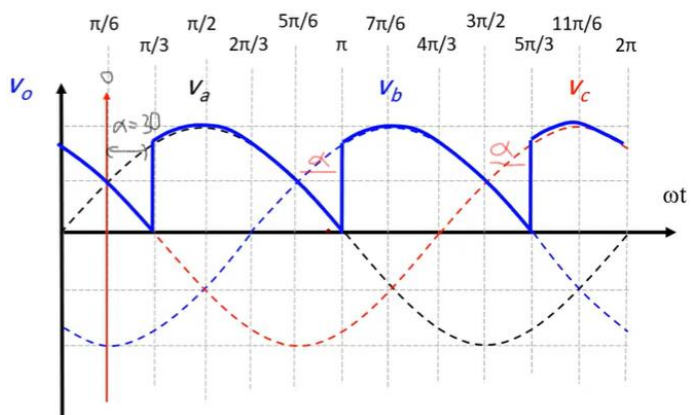
The expression of average or dc output voltage of a 3-phase half wave converter with resistive load can be applied to RL-load with Fwd.



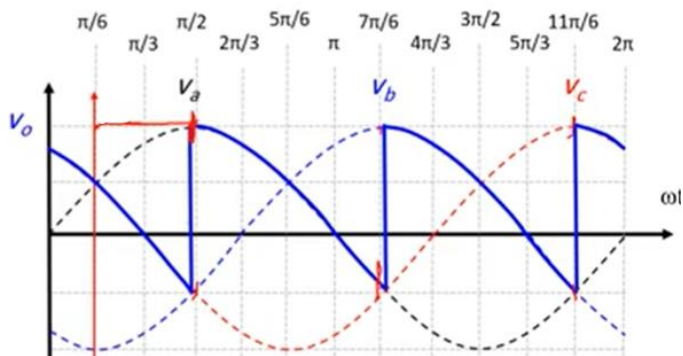
◆ Case of Rl- Load



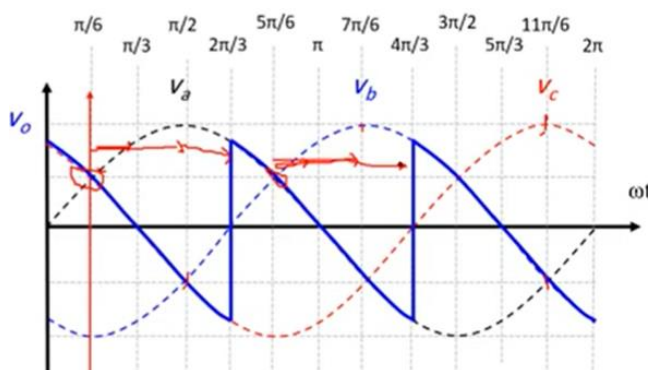
For Different Trigger Angles:



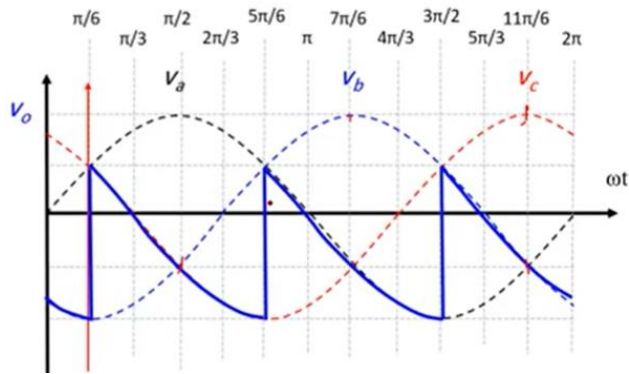
$\alpha = 30$



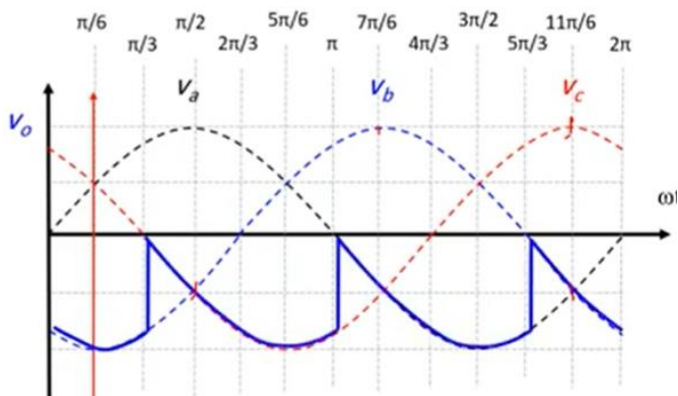
$\alpha = 60$



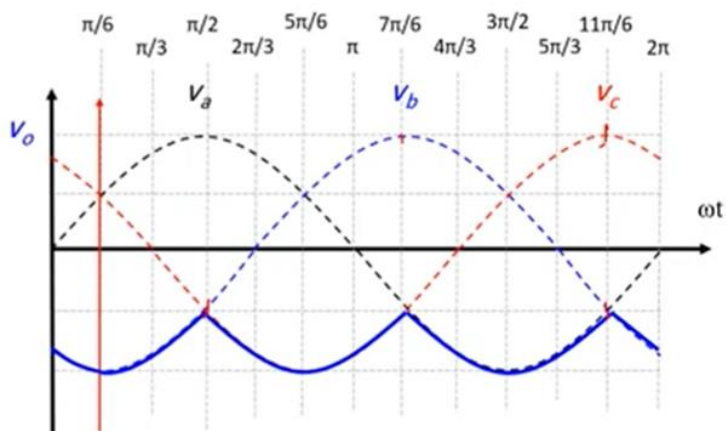
$\alpha = 90$



$$\alpha = 120$$



$$\alpha = 150$$



$$\alpha = 180$$

$$\alpha < 90$$

V_{dc} is positive

$$\alpha = 90$$

V_{dc} is zero

$$\alpha > 90$$

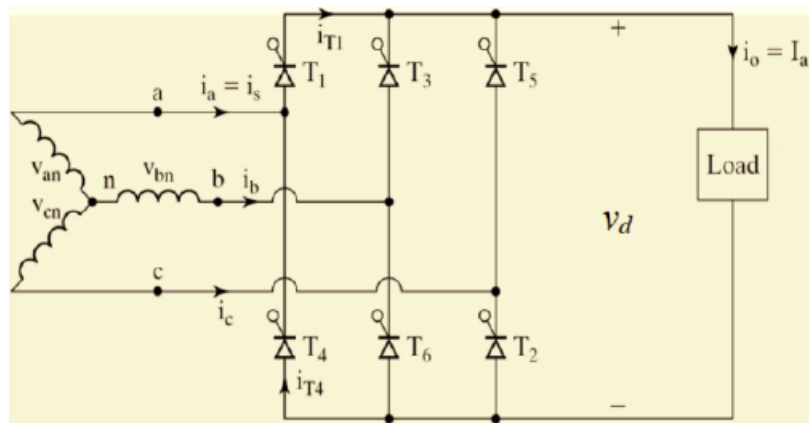
V_{dc} is negative

$$V_{dc} = \frac{3}{2\pi} \int_{\pi/6+\alpha}^{5\pi/6+\alpha} V_m \sin \omega t d(\omega t) = \frac{3\sqrt{3}V_m}{2\pi} \cos \alpha$$

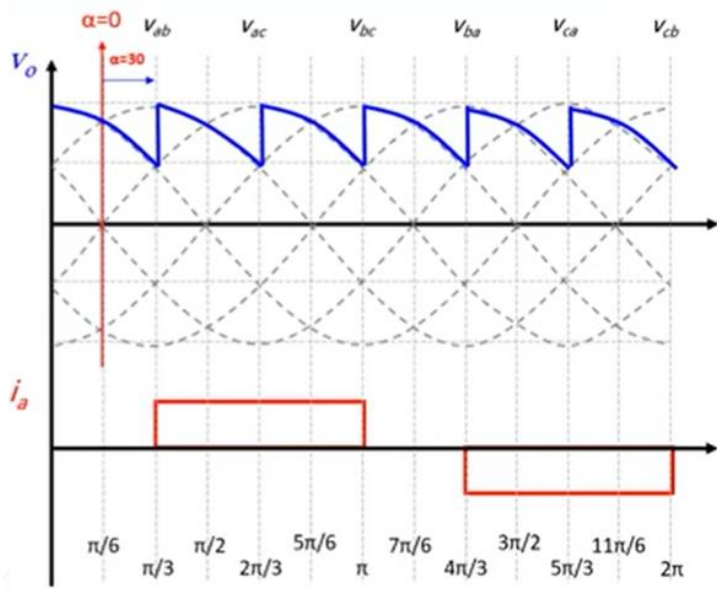
$$I_{DC} = I_{avg} = \frac{V_{dc}}{R} = \frac{3\sqrt{3}Vm}{2\pi R} \cos \alpha \cong I_{o,rms}$$

2) Full-Wave Rectifiers

Three-phase converters are extensively used in industrial applications up to the 120-kW level. The output of the three-phase rectifier can be controlled by substituting six SCRs for diodes connected in the form of a full wave bridge configuration. All six thyristors are turned on at an appropriate time by applying suitable gate trigger signals. This circuit is known as a three-phase full wave bridge or as a **six-pulse rectifier**.

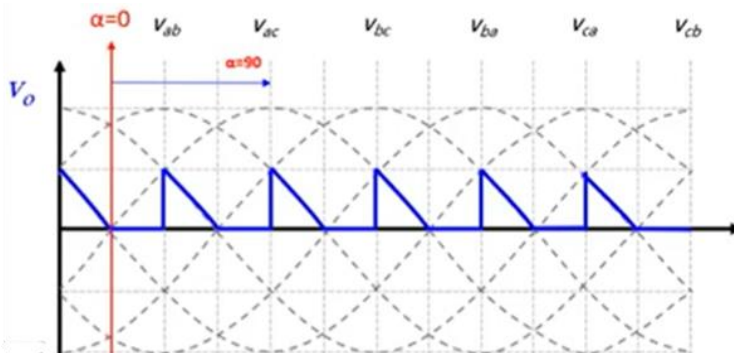
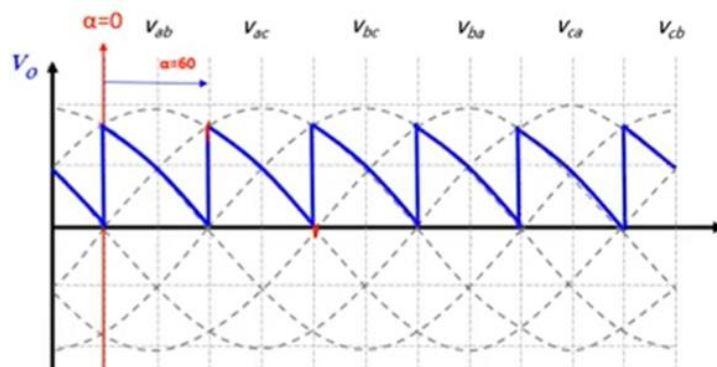


- The three thyristors (T₁, T₃ and T₅) will not work together at the same time or two of them also will not work together at the same time.
- The three thyristors (T₂, T₄ and T₆) will not work together at the same time or two of them also will not work together at the same time.
- (T₁ and T₄), (T₃ and T₆) or (T₅ and T₂) will not work together at the same time.
- Each thyristor is triggered at an interval of $2\pi/3$.
- Each thyristors pair ((T₆&T₁), (T₁&T₂), (T₂&T₃), (T₃&T₄), (T₄&T₅), (T₅&T₆)) is triggered at an interval of $\pi/3$.
- The frequency of output ripple voltage is $6f_s$.



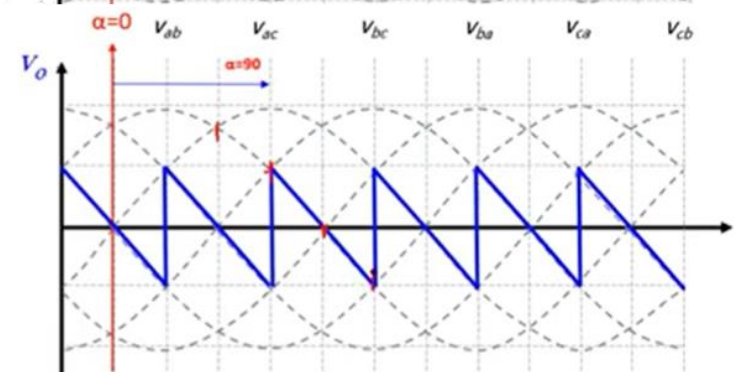
Same for R and RL load

$$0 \leq \alpha \leq 60$$



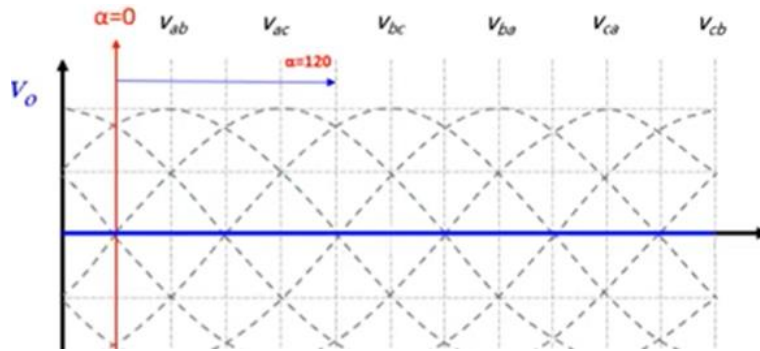
for R- load

$$\alpha=90$$



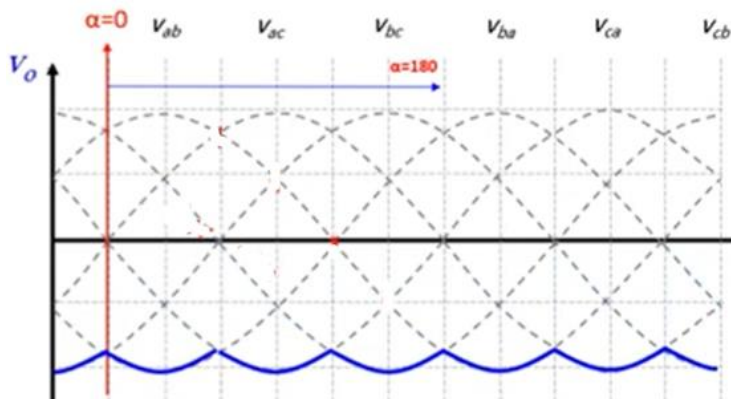
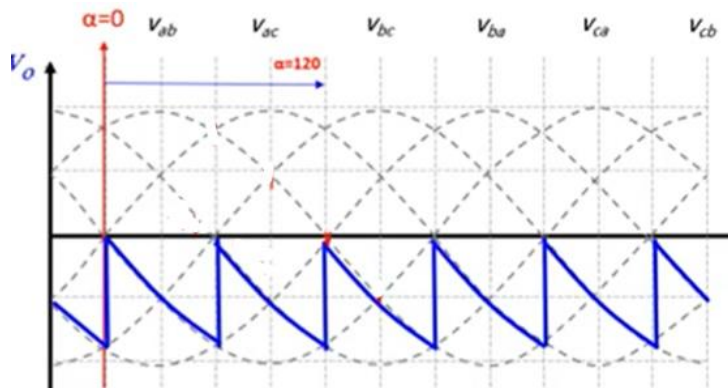
for RL- load

$$\alpha=90$$



for R- load

$\alpha = 120$



for RL- load

$\alpha = 120$

$$V_{dc} = \frac{3\sqrt{3}V_m}{\pi} \cos \alpha = \frac{3V_{mL}}{\pi} \cos \alpha$$

Where $V_{mL} = \sqrt{3}V_m = \text{Max. line-to-line supply voltage}$

the average output voltage is reduced as the delay angle α increases.

$$V_{rms} = \sqrt{3}V_m \sqrt{\frac{1}{2} + \frac{3\sqrt{3}}{4\pi} \cos 2\alpha}$$

$$I_{rms} = V_{rms} / R$$

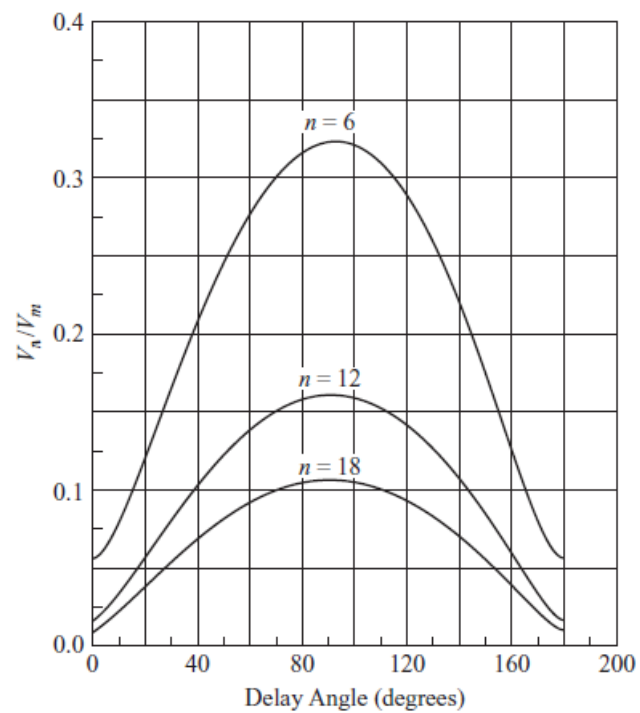
$$I_{rms} = \frac{V_{rms}}{\sqrt{R^2 + (\omega L)^2}} = \frac{\sqrt{3}V_m}{\sqrt{R^2 + (\omega L)^2}} \sqrt{\frac{1}{2} + \frac{3\sqrt{3}}{4\pi} \cos 2\alpha}$$

Special case: resistive load $\alpha > 60^\circ$

$$V_{dc} = \frac{3}{\pi} \int_{\frac{\pi}{6} + \alpha}^{\pi} \sqrt{3}V_m \sin(\omega t + \frac{\pi}{6}) d\omega t = \frac{3\sqrt{3}V_m}{\pi} \cos(\frac{\pi}{3} + \alpha)$$

$$I_{dc} = \frac{V_{dc}}{R} = \frac{3\sqrt{3}V_m}{\pi R} \cos(\frac{\pi}{3} + \alpha)$$

Harmonics for the output voltage remain of order 6k, but the amplitudes are functions of α . The figure shows the first three normalized harmonic amplitudes.



Example

The three-phase controlled rectifier of Fig. 4-20a is supplied from a 4160-V rms line-to-line 60-Hz source. The load is a 120- Ω resistor. (a) Determine the delay angle required to produce an average load current of 25 A. (b) Estimate the amplitudes of the voltage harmonics V_6 , V_{12} , and V_{18} .

Solution:

$$a) V_o = I_o R = (25)(120) = 3000 \text{ V.}$$

$$\alpha = \cos^{-1} \left(\frac{\pi V_o}{3V_m} \right) = \cos^{-1} \left(\frac{\pi 3000}{3\sqrt{2}(4160)} \right) = 57.7^\circ$$

$$b) \text{ From Fig. } \frac{V_6}{V_m} \approx 0.28 \Rightarrow V_6 = 0.28\sqrt{2}(4160) = 1640 \text{ V.}$$

$$\frac{V_{12}}{V_m} \approx 0.135 \Rightarrow V_{12} = 794 \text{ V.}$$

$$\frac{V_{18}}{V_m} \approx 0.09 \Rightarrow V_{18} = 525 \text{ V.}$$

Example:

The six-pulse controlled three-phase converter is supplied from a 480-V rms line-to-line 60-Hz three-phase source. The delay angle is 35° , and the load is a series RL combination with $R = 50 \Omega$ and $L = 50 \text{ mH}$. Determine (a) the average current in the load, (b) the amplitude of the sixth harmonic current, and (c) the rms current in each line from the ac source.

Sol/

$$a) V_o = \frac{3V_m}{\pi} \cos \alpha = \frac{3\sqrt{2}(480)}{\pi} \cos 35^\circ = 531 \text{ V.}$$

$$I_o = \frac{V_o}{R} = \frac{531}{50} = 10.6 \text{ A.}$$

$$b) \frac{V_6}{V_m} \approx 0.19 \Rightarrow V_6 = 0.19\sqrt{2}(480) = 130 \text{ V.}$$

$$Z_6 = |R + j6\omega_0 L| = |50 + j6(377)(0.05)| = 124 \Omega$$

$$I_6 = \frac{V_6}{Z_6} = \frac{130}{124} = 1.05 \text{ A.}$$

$$I_{o,rms} \approx \sqrt{i_o^2 + \left(\frac{I_6}{\sqrt{2}} \right)^2} = \sqrt{10.6^2 + \left(\frac{1.05}{\sqrt{2}} \right)^2} = 10.65 \text{ A.}$$

$$I_{s,rms} = \left(\sqrt{\frac{2}{3}} \right) I_{o,rms} = \left(\sqrt{\frac{2}{3}} \right) 10.65 = 8.6 \text{ A.}$$

The six-pulse controlled three-phase converter of Problem 12 is supplied from a 480-V rms line-to-line 60-Hz three-phase source. The delay angle is 50° , and the load is a series RL combination with $R = 10\ \Omega$ and $L = 10\text{ mH}$. Determine (a) the average current in the load, (b) the amplitude of the sixth harmonic current, and (c) the rms current in each line from the ac source.

$$a) \ V_o = \frac{3V_m}{\pi} \cos \alpha = \frac{3\sqrt{2}(480)}{\pi} \cos 50^\circ = 417\text{ V}.$$

$$I_o = \frac{V_o}{R} = \frac{417}{10} = 41.7\text{ A}.$$

$$b) \ \frac{V_6}{V_m} \approx 0.25 \Rightarrow V_6 = 0.25\sqrt{2}(480) = 170\text{ V}.$$

$$Z_6 = |R + j6\omega_0 L| = |10 + j6(377)(0.01)| = 24.7\ \Omega$$

$$I_6 = \frac{V_6}{Z_6} = \frac{170}{24.7} = 6.9\text{ A}.$$

$$I_{o,rms} \approx \sqrt{i_o^2 + \left(\frac{I_6}{\sqrt{2}}\right)^2} = \sqrt{41.7^2 + \left(\frac{6.9}{\sqrt{2}}\right)^2} = 42.3\text{ A}.$$

$$I_{s,rms} = \left(\sqrt{\frac{2}{3}}\right) I_{o,rms} = \left(\sqrt{\frac{2}{3}}\right) 41.7 = 34\text{ A}.$$

The six-pulse controlled three-phase converter of Fig. 10-10 is supplied from a 480-V rms line-to-line 60-Hz three-phase source. The load is a series RL combination with $R = 20\ \Omega$. (a) Determine the delay angle required for an average load current of 20 A. (b) Determine the value of L such that the first ac current term ($n = 6$) is less than 2 percent of the average current. (c) Verify your results with a PSpice simulation.

$$a) \quad V_o = I_o R = (20)(20) = 400\text{ V}.$$

$$\alpha = \cos^{-1} \left(\frac{\pi V_o}{3V_m} \right) = \cos^{-1} \left(\frac{\pi 400}{3\sqrt{2}(480)} \right) = 52^\circ$$

$$b) \quad \frac{V_6}{V_m} \approx 0.25 \Rightarrow V_6 = 0.25(\sqrt{2})(480) = 170\text{ V}.$$

$$\sqrt{\left(\frac{I_6}{\sqrt{2}} \right)^2 + \left(\frac{I_{12}}{\sqrt{2}} \right)^2 + \left(\frac{I_{18}}{\sqrt{2}} \right)^2} < 0.02 I_o \quad \text{or} \quad \sqrt{I_6^2 + I_{12}^2 + I_{18}^2} < 0.02\sqrt{2} I_o$$

$$Z_6 = |R + j6\omega L|$$

$$\frac{V_6}{Z_6} = I_6 < 0.02 I_o = 0.02(20) = 0.4\text{ A}.$$

$$Z_6 = \frac{V_6}{I_6} = \frac{170}{0.4} = 425\ \Omega = |R + j6\omega L| = |20 + j6(377)L|$$

$$6(377)L \approx 425$$

$$L = \frac{425}{6(377)} = 0.188\text{ H}$$

$$L \approx 190\text{ mH}$$